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# Language & System Support for Efficient State Sharing in Distributed Stream Processing Systems

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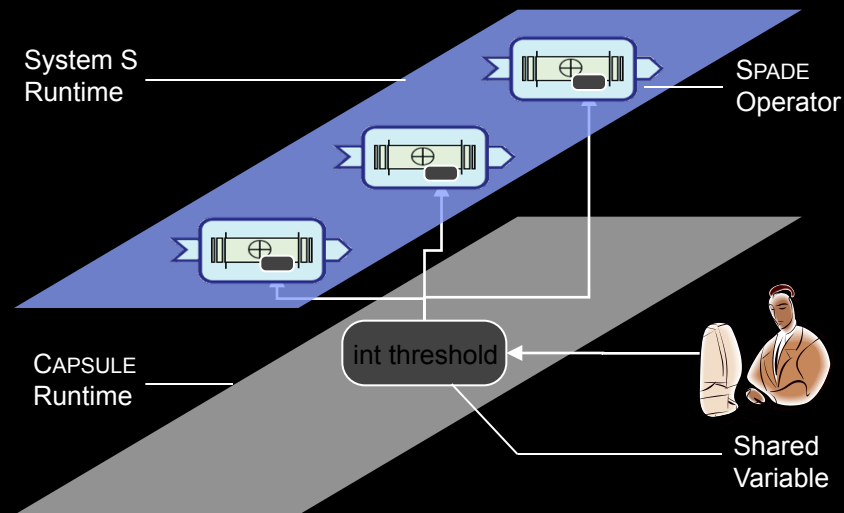
## Outline

- Motivation
- Design considerations
- Detailed design
- Implementation & evaluation
- Summary

## What is the need for state sharing in stream processing systems?

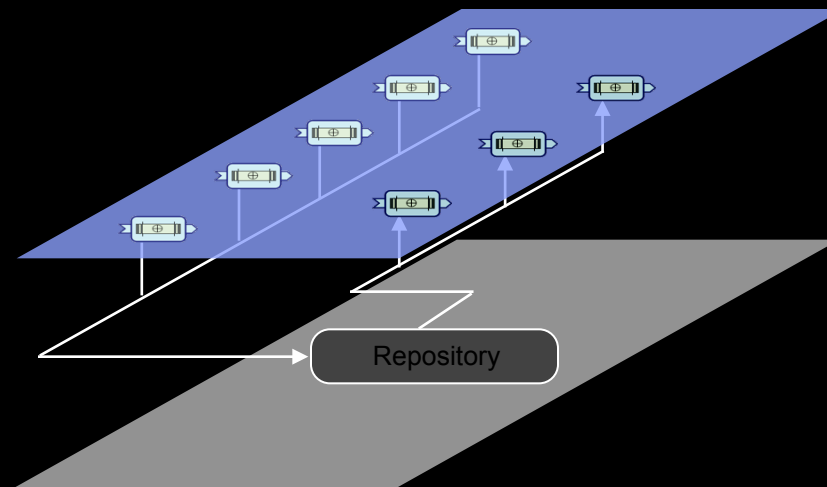
### ■ Control Variables

- In a long running System S application, a user may want to modify the behavior of some operators at runtime
- Examples: *filtering threshold, routing behavior, lookup tables etc.*

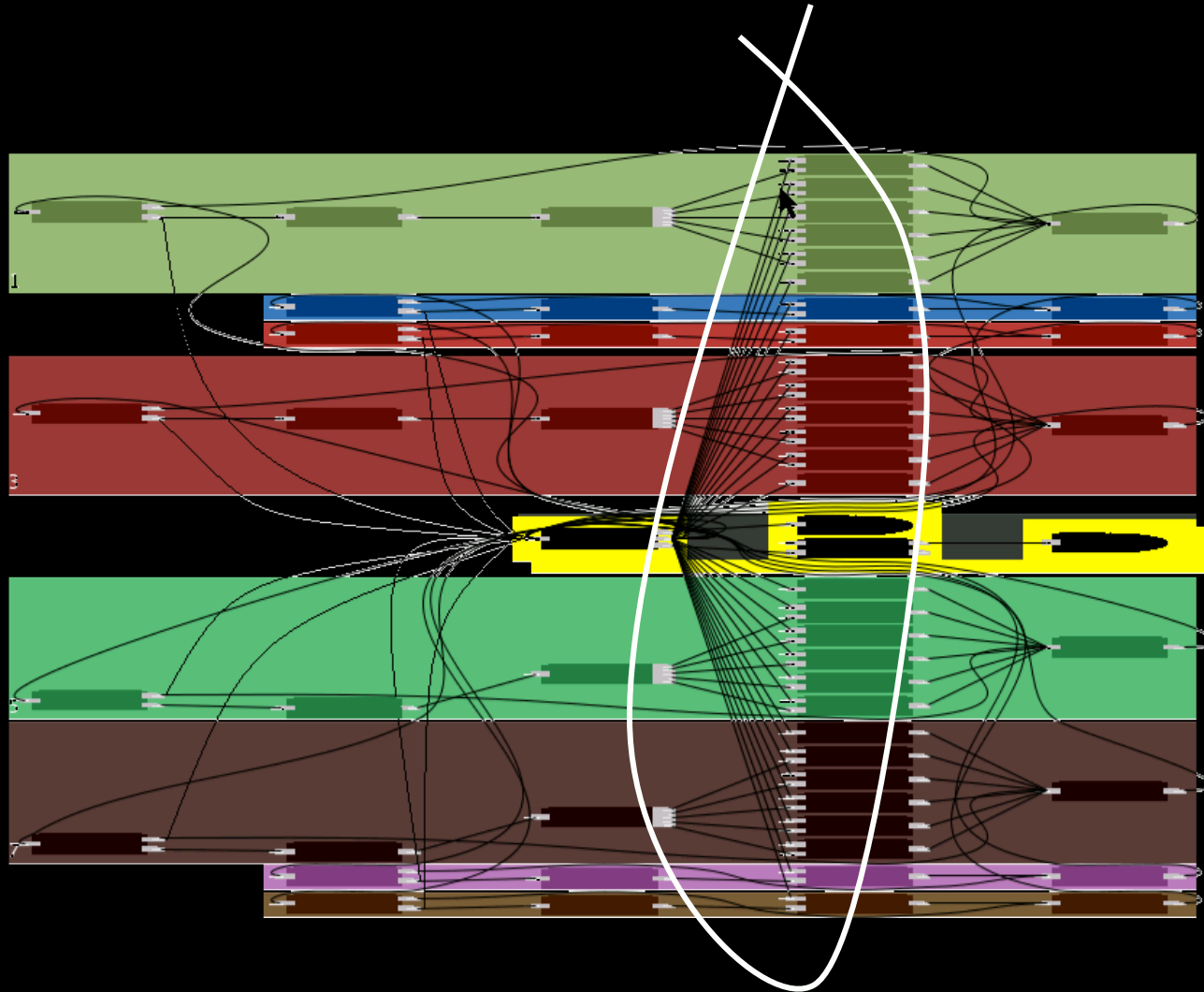


## What is the need for state sharing in stream processing systems?

- A shared runtime repository of interesting events
  - Operators collaborate to detect and follow-up on interesting events observed by the application
  - Examples: *intrusion detection*



## Why not use System S to propagate updates? – Control spaghetti



## Efficient state sharing in stream processing systems - Why is it hard?

- **Ease-of-use & Flexibility**
  - Many System S users are domain experts and/or analysts with sufficient but not a deep understanding of issues related to distributed shared state.
  - System S is used for a range of applications (e.g. healthcare, telecommunications, finance, etc.) that have very different expectations from shared state implementation.
- **Scalability, High-Performance & Fault-Tolerance**
  - The state sharing mechanism should be such that it limits the impact on the scalability and performance of the System S application. Also, the exposure of the user to issues like fault-tolerance of the shared state should be minimized.
- **Relaxed Consistency Guarantees**
  - Given the fact that many System S applications do not require atomic consistency for access to the shared state, the state sharing mechanism should be able to exploit the relaxed consistency requirements for enhanced scalability and/or performance.

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## **Ease-of-use & Flexibility**

SPADE language constructs

What were we thinking?

Provide flexibility to users while maintaining the ease of use



## Ease-of-use & Flexibility: SPADE language constructs

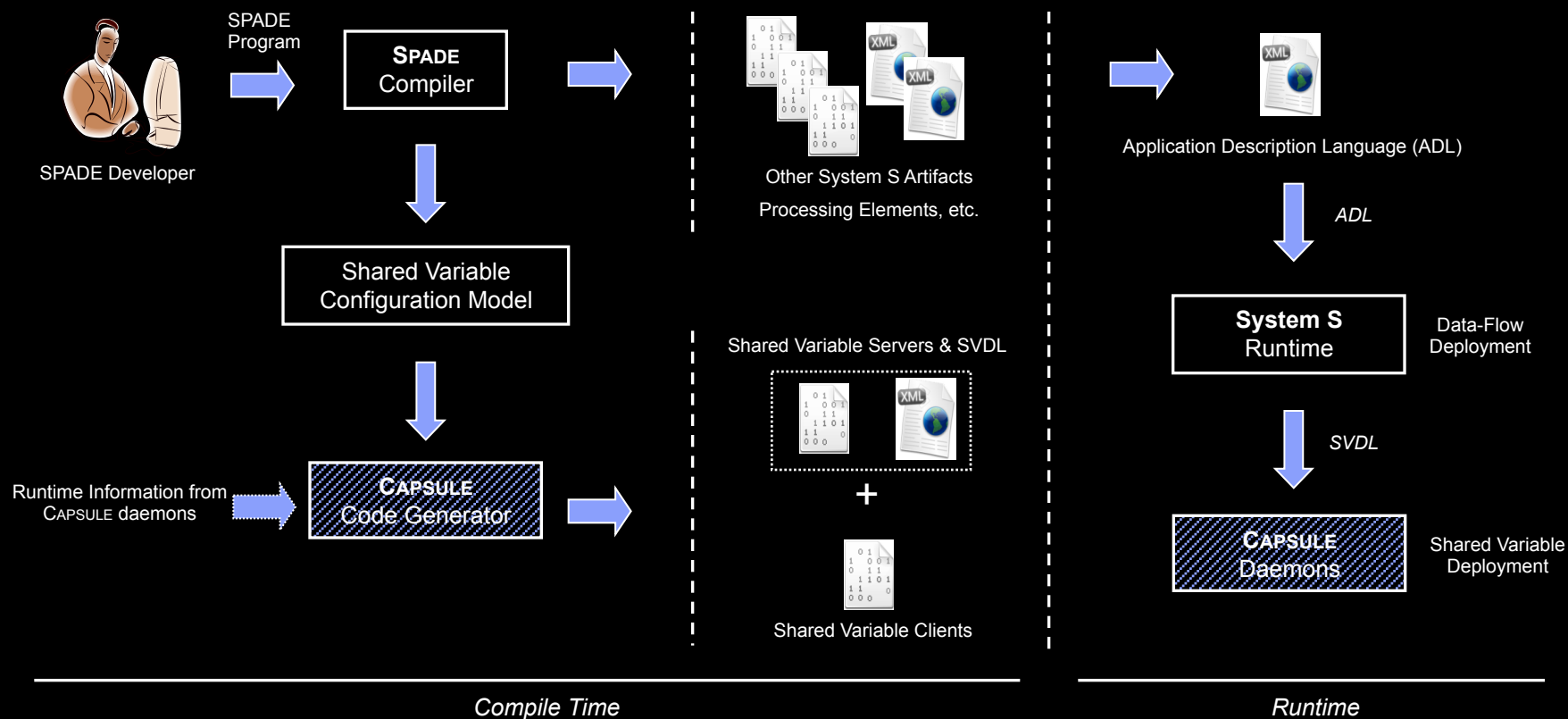
```
sharedVarDef ::= sharedVarModifier* type ID ( = expr )? sharedVarConfigs  
sharedVarModifier ::= 'public' | 'static' | 'mutable'  
sharedVarConfigs ::= ';' | '{' 'config' configuration+ '}'
```

- *public* – may be used from anywhere in the system
- *static* – all instance of the operator defining the shared variable will share the same copy
- *mutable* – can be modified
- *configuration* – name-value pair

## Example usage

```
composite CompositeWithSharedVariables(Output out; Input in){  
    var    int32 s_thresh = 10;  
    public static mutable map<string8, int32> s_map {  
        config lifetime      : eternal;  
        consistency          : causal;  
        sizeHint              : 1024 * 128 * 128;  
    }  
    graph stream<In> X = ClassifierX(In){ param cMapX   : s_map; }  
    stream<In> Y = ClassifierY(In){ param cMapY   : s_map; }  
    stream<In> Out = Functor(X,Y){ param filter : x > s_thresh; }  
}
```

## Once the shared variables are defined in a SPADE program...



## Compile Time

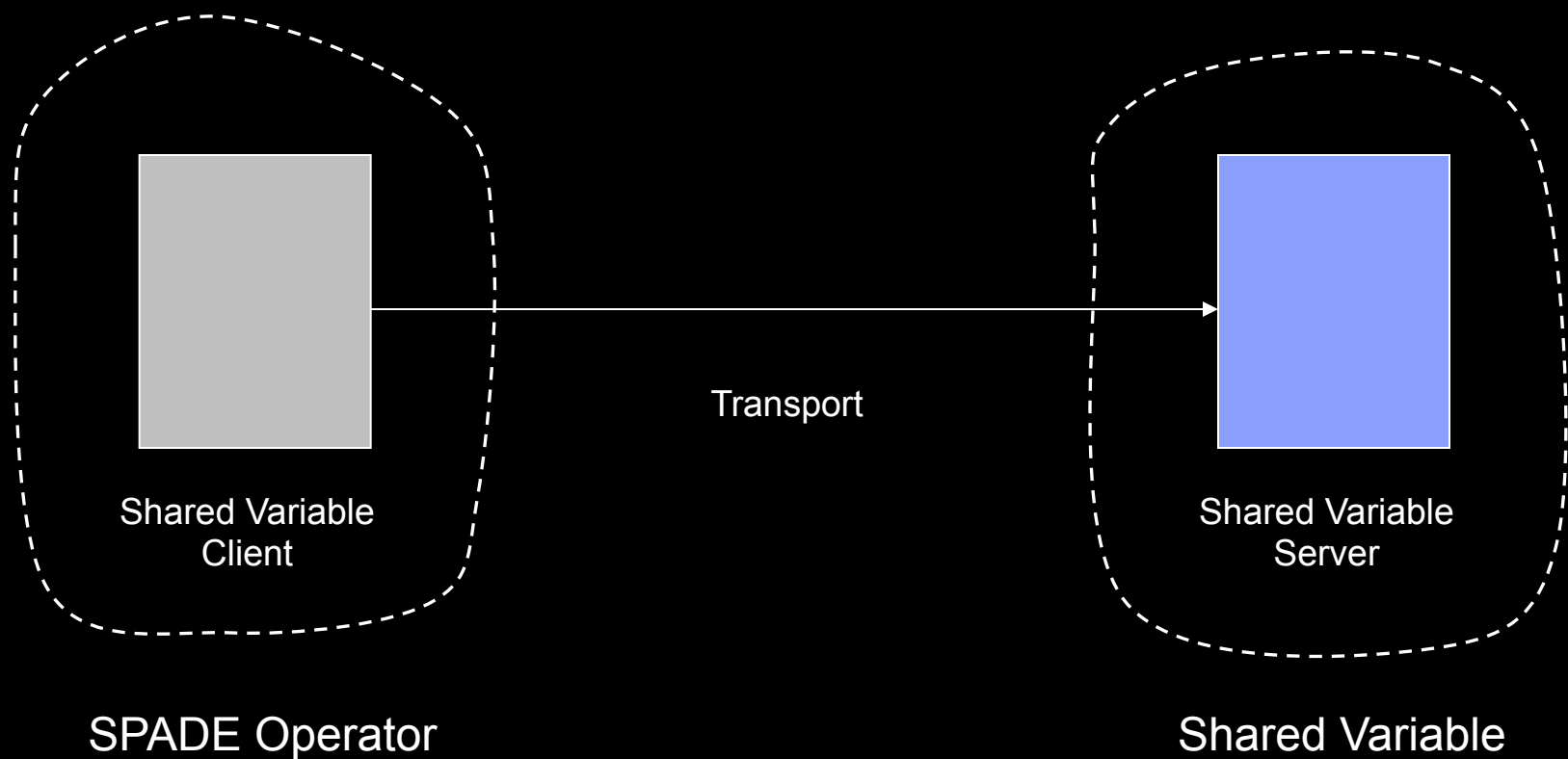
Shared variable data types

What were we thinking?

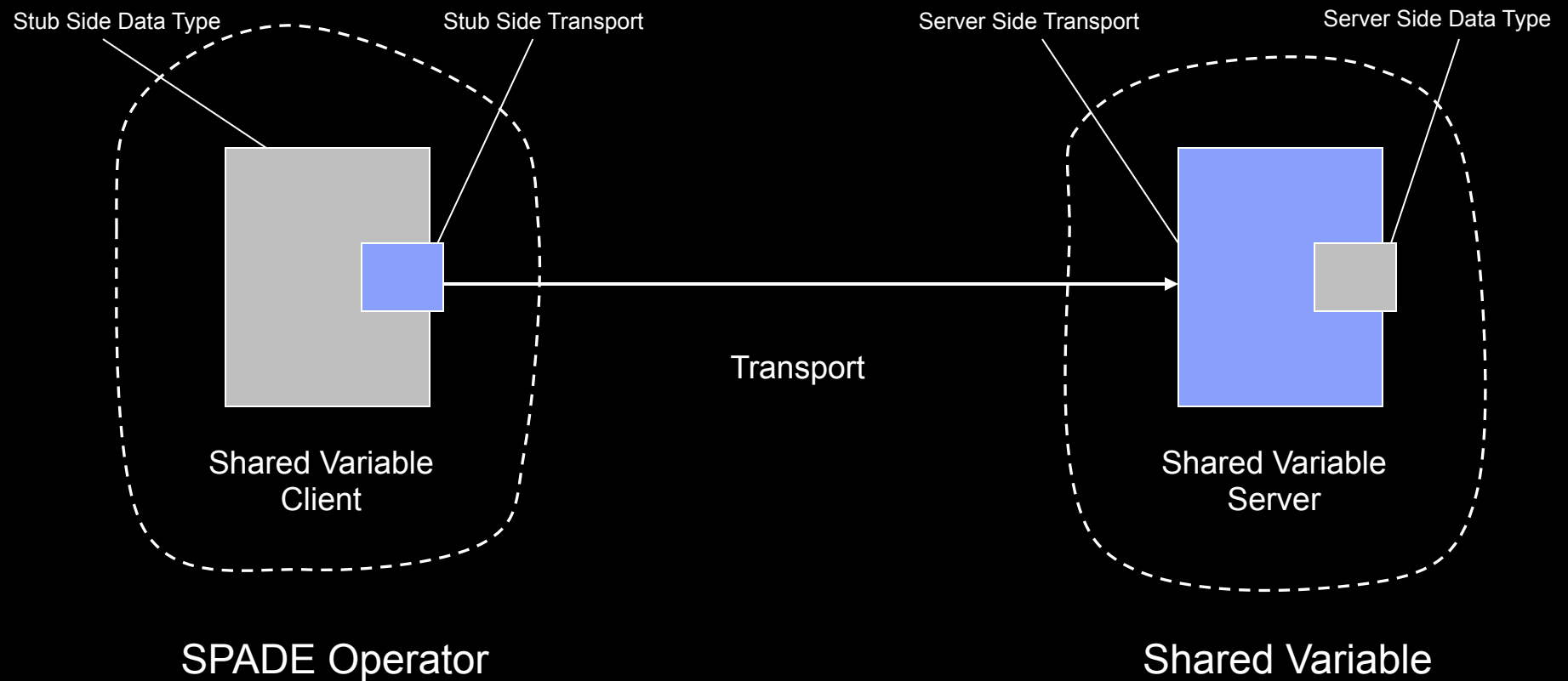
State sharing should be transparent

Shared Variable data types should be oblivious of the transport and/or protocol

## A view of Shared Variable from 30,000 feet



## A view of Shared Variable from 20,000 feet



## Client / Server side data types and `invoke` interface

Stub Side Data Type

```
+ - * /
% += -=
*= /= %=
++ --
& | ^ ~
```

**SVInteger**

Server Side Data Type

```
int32 get();
void set(int32);
int32 add(int32);
int32 subtract(int32);
int32 multiply(int32);
int32 divide(int32);
int32 modulo(int32);
```

`invoke`  
Interface

Calls  
`invoke`  
Interface

Implements  
`invoke`  
Interface

```
void invoke(int methodIndex, Buffer inParams, Buffer outParams);
```

## Example Shared Variable data type

- Server side data type

```
SVIntegerServer<T>  
[T = int8, int16, int32, int64]
```

- Stub side data type

```
SVIntegerClient<T,I>  
[T = int8, int16, int32, int64]  
[I = SVBasicInterfaceCorbaClientImpl, ...]
```



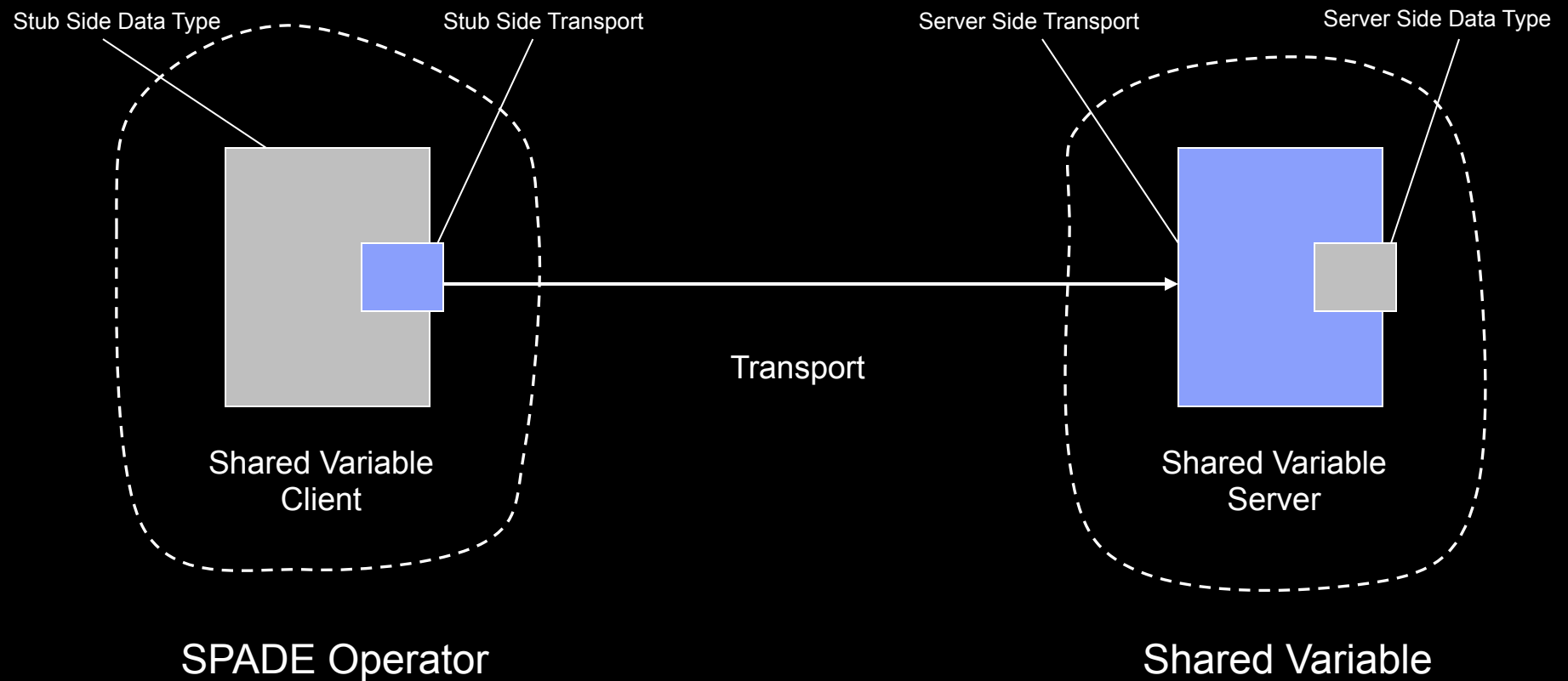
## **Compile time**

Shared Variable transport and protocol

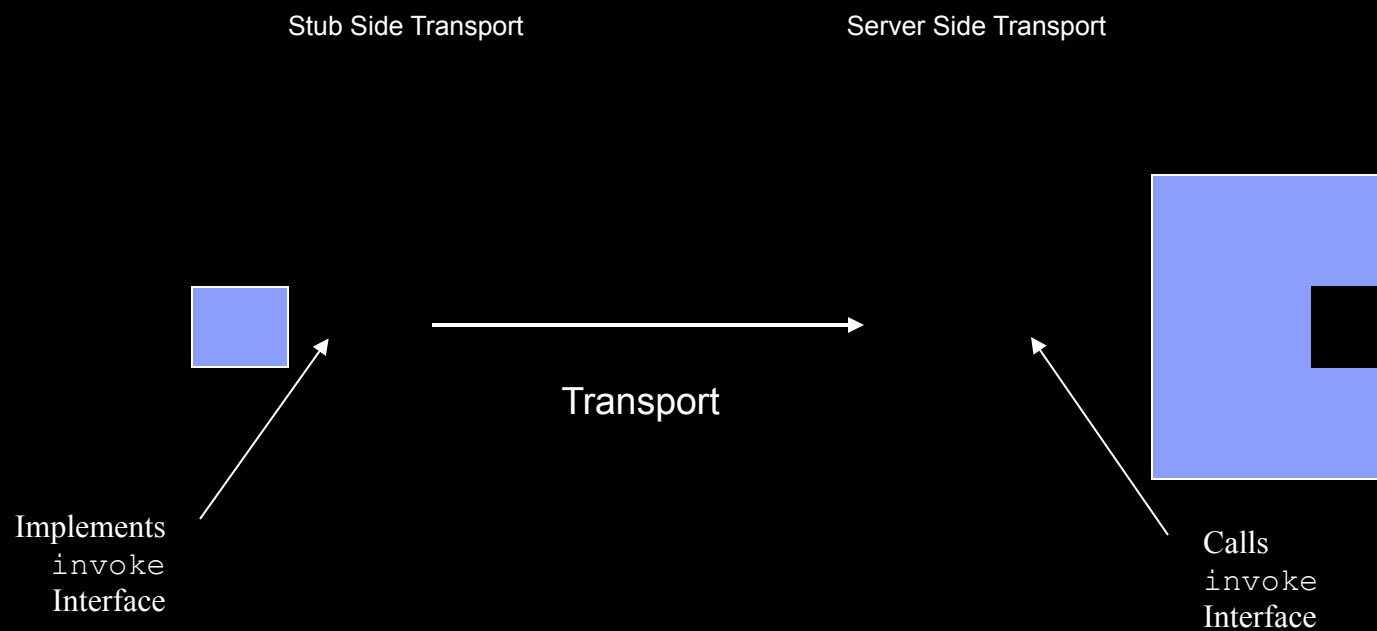
What were we thinking?

Should be usable with any compatible data client / server

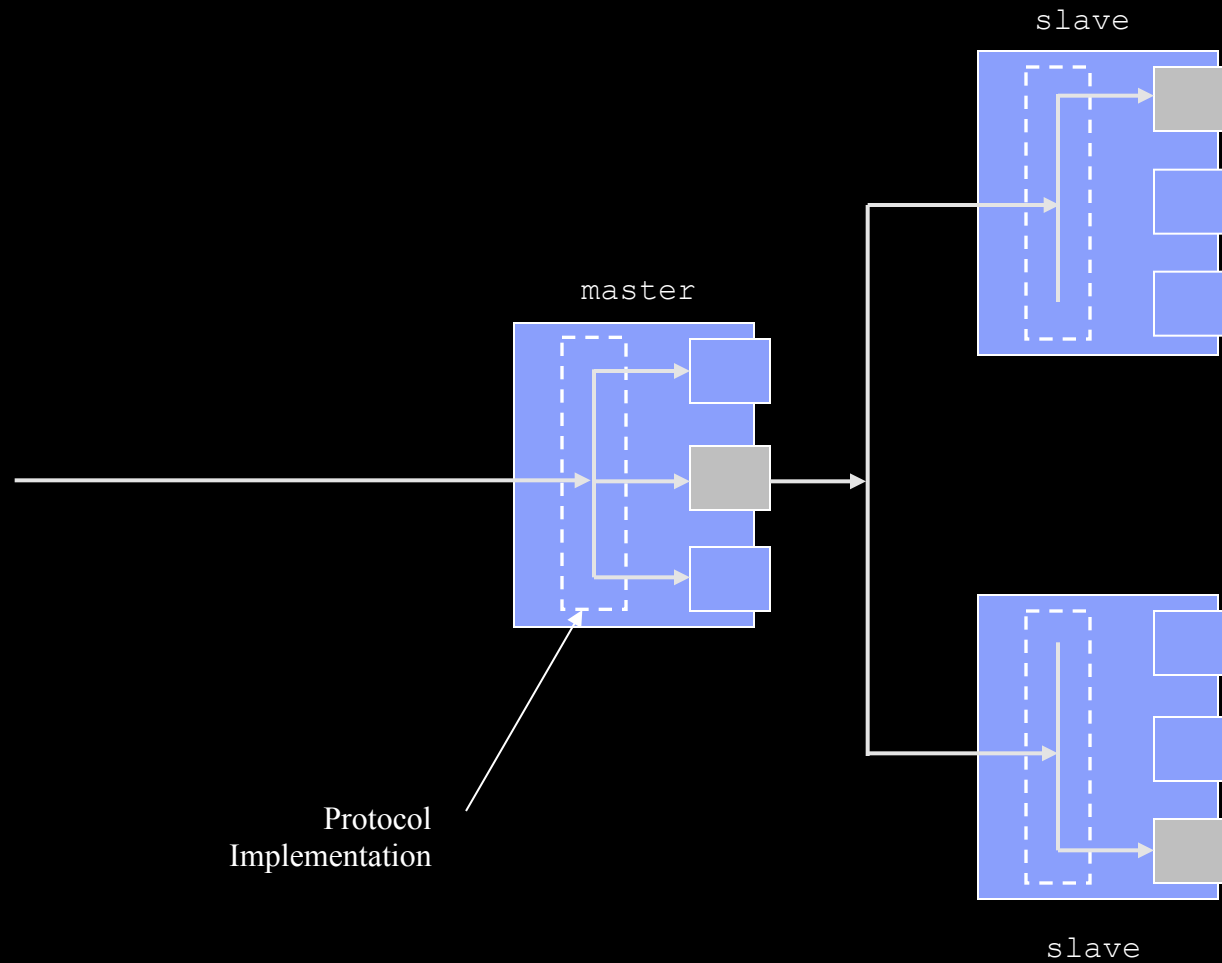
## A view of Shared Variable from 20,000 feet



## Shared Variable transport



## Shared Variable protocol implementation



## Example Shared Variable transport and protocol

- Server side transport and protocol type

```
SVBasicInterfaceCorbaServerImpl<T>  
[T = SVInteger, SVFloat, ...]
```

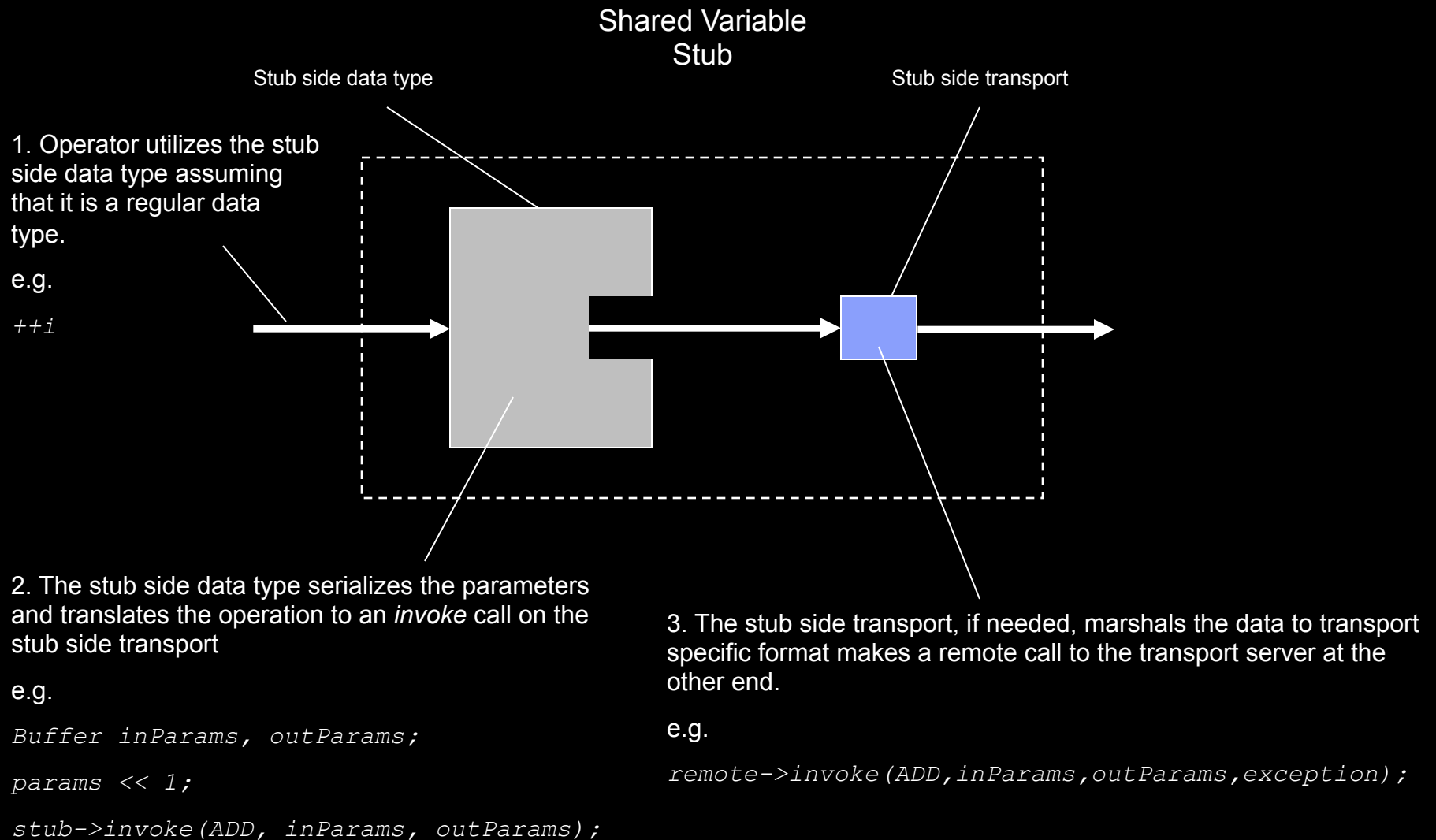
- Client side transport and protocol type

```
SVBasicInterfaceCorbaClientImpl
```

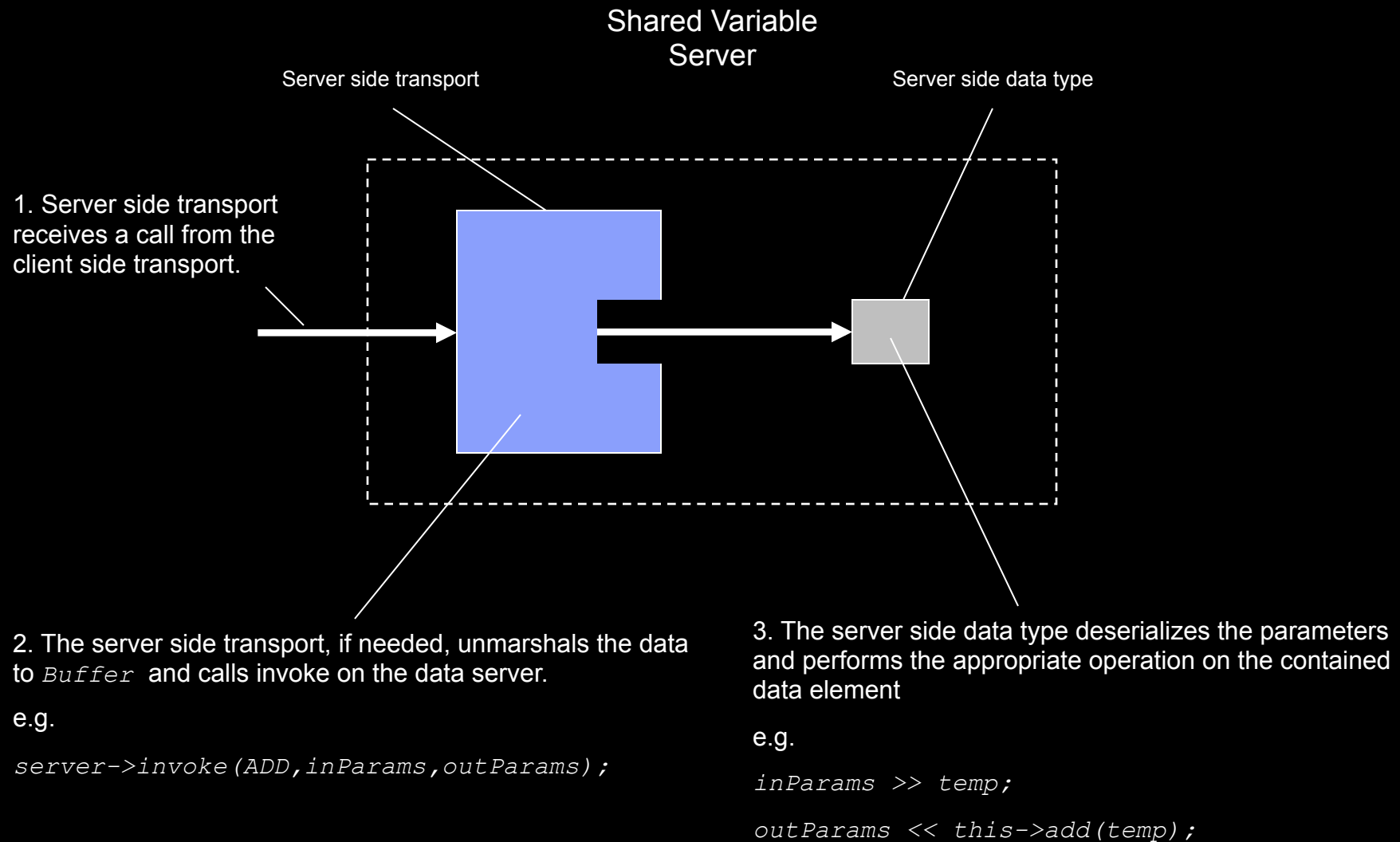
## **Compile time**

Shared variable servers, clients and the SVDL – putting it together

## Shared Variable stub

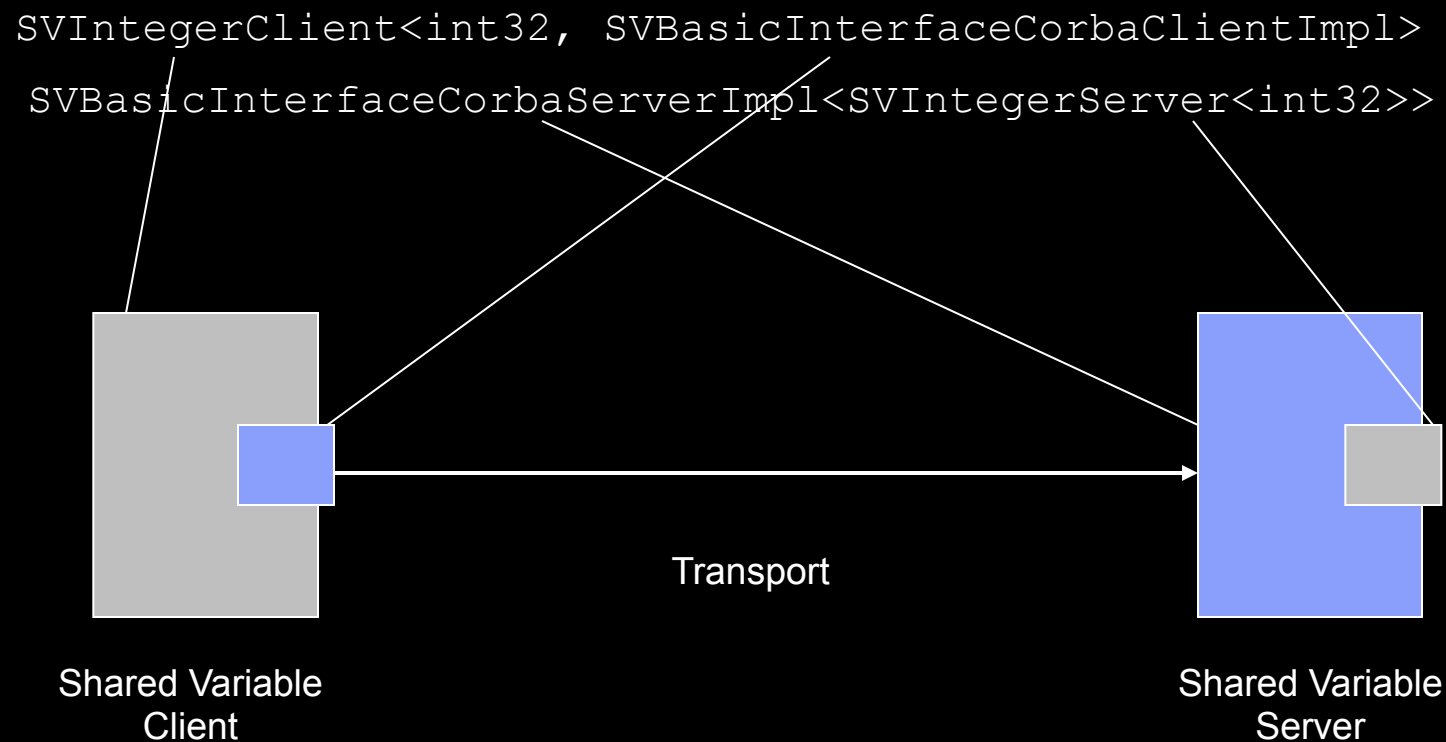


## Shared Variable server





## Shared Variable stub and server example



## Shared variable description language (SVDL)

- Describes the composition of a shared variable
- Various constructs
  - Base variable
    - refers to a shared variable server, needs dll and location
  - Variable group
    - a protocol governed group of base variable, shared variable and / or variable group
  - Shared variable
    - contains a base variable or a variable group and has a name
- Is part of the Application Definition Language and is loaded by the Shared variable daemon at deployment time

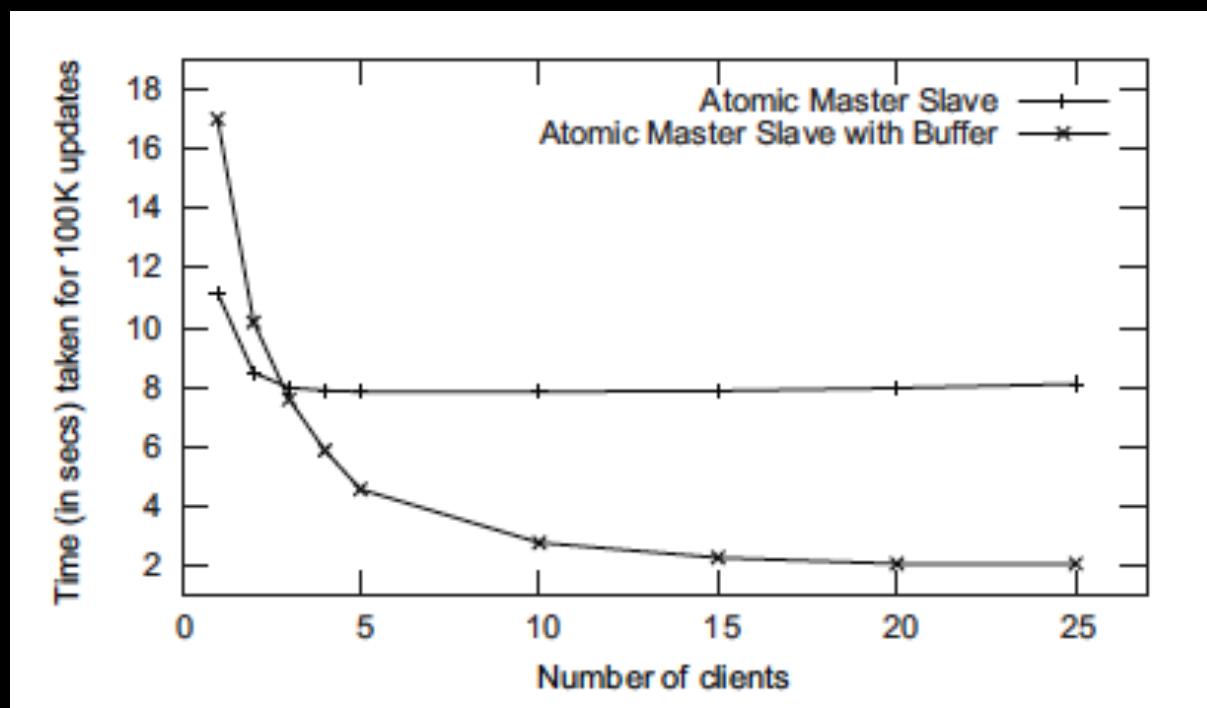
## SVDL example

```
<sharedVariable>
  <name>A</name>
  <variableGroup>
    <protocol>Atomic</protocol>
    <baseVariable>
      <dll>/users/omega/abc.so</dll>
      <location>192.168.2.101</location>
    </baseVariable>
    <baseVariable>
      <dll>/users/omega/abc.so</dll>
      <location>192.168.2.102</location>
    </baseVariable>
  </variableGroup>
</sharedVariable>
```

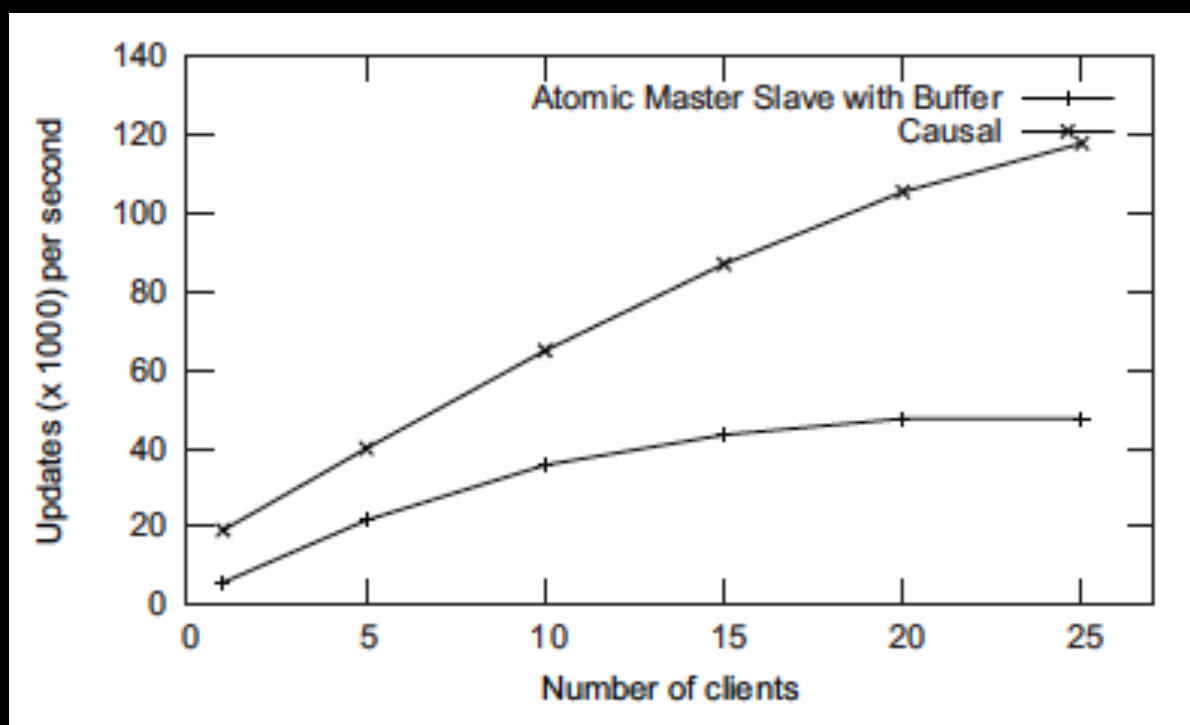
## Implementation & Evaluation

- Besides the implementation of data types, we have a transport implementation based on CORBA.
- We have implemented 4 protocols – Atomic Master-Slave, Atomic Master-Slave with Buffer, Causal and Partitioned protocol. Other implementations will follow.
- The reported experiments were conducted on a 2 x dual core machines @ 3.0 GHz with 8 GB RAM

## Comparison between performance of AMS and AMSB



## Comparison between performance of AMSB and Causal protocol



## Summary & Future Work

- Shared variables in System S attempt to exploit configuration parameters to code generate a customized implementation for higher performance
- Maintaining conformity to SPADE's native data types makes it simple to program using Shared Variables
- Initial scalability and performance results seem to be very promising
- Work is ongoing to determine the best heuristic that translates configuration parameters (e.g. readsPerSecond, writesPerSecond, consistency, etc.) to the most appropriate generated code for shared variables
- Work is ongoing to incorporate the dependency between various clients (operators) into the Shared Variable consistency model

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Thank You!